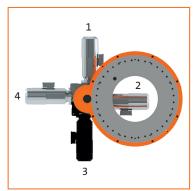


FIBROMAT HEAVY-LOAD POSITIONING TABLES

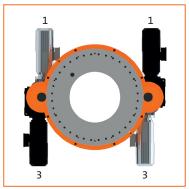
DATA SHEET COLLECTION



FIBRO



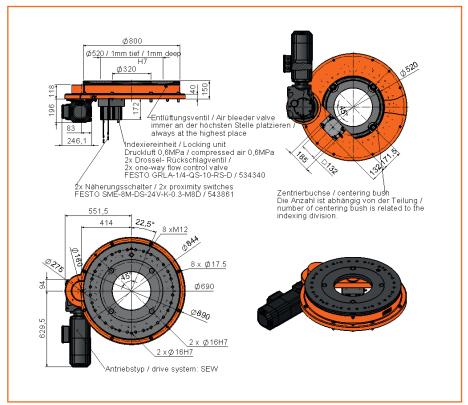
FIBROMAT AT.0800 Drive arrangement 10, 20, **30**, 40



FIBROMAT AT.0800 Drive arrangement 11, 13, **31**, 33

Dimensions of FIBROMAT® AT.0800

(Drive arrangement 180° with one drive; for other drive arrangements, diagrams or CAD data are available)



Technical data for FIBROMAT® AT.0800

	2		3	0	Ð	(5) (6
AT.0800		. [Ī

Table top dimension	Ø 800 mm					
Drive motor	1 drive without motor 1 drive with motor 1 drive with motor 1 drive with motor 2 drives without motor 2 drives with motor 2 drives with motor 2 drives with motor 2 drives with motor	SEW asynchronous servo g SIEMENS Motor 1FK710 Special motor Gearboxes prepared for	motors according to customer gear motor KF57/R DRL 90L4BE2/TF/AS7W/Z	.10 .11 .12 .19 .20 .21 .22	2	
Drive arrangement	See pictures above Special design			.XX .99	3	
Divisions Any, maximum 16	Without indexing unit With indexing unit for di Special division	Nith indexing unit for division XX, symmetrical arrangement				
Centre hole	Ø 320 mm Extended by 200 mm (no Special design	Extended by 200 mm (not combinable with standard indexing unit)				
Measuring system	Measuring system on mo With additional direct m With measuring system	easuring system (mount	ed in standard centre hole)	.0 .1 .9	6	
Direction of rotation	Any					
Mounting position	Any, standard table top: (Please state other mour	horizontal nting positions when orde	ering)			
Indexing and repeat accuracy No indexing, one drive No indexing, two drives With indexing, one drive With two drives, with measuring system	Indexing accuracy					

Maximum axial runout of the table top	0.05 mm	
Maximum runout of the centre hole	0.05 mm	
Weight	FIBROMAT AT.0800 Gear motor Indexing unit	350 kg 53 kg 25 kg

Indexing times for FIBROMAT® AT.0800

AT.0800	AT.0800 with one drive											
45°	t _s in s	2.7	2.4	2.1	1.9	1.7	1.3	1.0				
	J in kgm²	8,000	6,000	4,000	3,000	2,000	1,000	500				
90°	t _s in s	3.8	3.4	3.1	2.9	2.5	1.9	1.6				
	J in kgm²	8,000	6,000	4,000	3,000	2,000	1,000	500				
180°	t _s in s	5.7	5.3	4.8	4.2	3.6	3.1	2.8				
	J in kgm²	8,000	6,000	4,000	3,000	2,000	1,000	500				

AT.0800	with two drives							
45°	t _s in s	1.8	1.6	1.5	1.4	1.1	0.9	0.8
	J in kgm²	8,000	6,000	4,000	3,000	2,000	1,000	500
90°	t _s in s	2.8	2.6	2.2	1.9	1.7	1.5	1.3
	J in kgm²	8,000	6,000	4,000	3,000	2,000	1,000	500
180°	t _s in s	4.6	4.5	3.4	3.1	2.9	2.6	2.5
	J in kgm²	8,000	6,000	4,000	3,000	2,000	1,000	500

The specified switching times do not include: Regulation time of $0.1\,\mathrm{sec}$, indexing time of $0.3\,\mathrm{sec}$. Further angels and indexing times can be calculated for you.

Load data for FIBROMAT® AT.0800

Perm. transport load on table top horizontal	10.000 kg
Perm. superstructure diameter	4.500 mm
Perm. force vertically on rotating table top	141.000 N
Perm. radial force on the rotating table top	56.000 N
Perm. tilting moment on rotating table top	35.000 Nm
Perm. tangential moment on table top (dynamic)	6.500 Nm

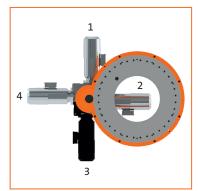
We would be pleased to provide a calculation of combined load data for your specific application.

Additional options for FIBROMAT® AT.0800

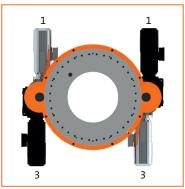
Drive unit Asynchronous motor (standard)	Indexing unit	
Drive unit Synchronous servomotor	Machine stands Height: 397 mm	FIBRO
Drive inverter	Additional table top	

CAD data, technical data and planning documentation can be downloaded from www.fibro.com.

FIBRO



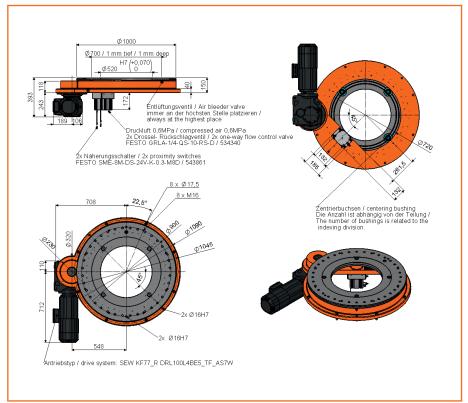
FIBROMAT AT.1000 Drive arrangement 10, 20, **30**, 40



FIBROMAT AT.1000 Drive arrangement 11, 13, **31**, 33

Dimensions of FIBROMAT® AT.1000

(Drive arrangement 180° with one drive; for other drive arrangements, diagrams or CAD data are available)



Technical data for FIBROMAT® AT.1000

	(2	2)	(3)	(Ð	(3) (0
AT.1000										

Table top dimension	Ø 1,000 mm					
Drive motor	1 drive without motor 1 drive with motor 1 drive with motor 1 drive with motor 2 drives without motor 2 drives with motor 2 drives with motor 2 drives with motor 2 drives with motor	SEW asynchronous servo g SIEMENS Motor 1FK710 Special motor Gearboxes prepared for	motors according to customer ear motor KF77/R DRL 100L4BE5/TF/AS7W/Z	.10 .11 .12 .19 .20 .21 .22	2	
Drive arrangement	See pictures above Special design			.XX .99	3	
Divisions Any, maximum 22	Without indexing unit With indexing unit for di Special division	Nith indexing unit for division XX, symmetrical arrangement				
Centre hole	Ø 520 mm Extended by 200 mm (no Special design	Extended by 200 mm (not combinable with standard indexing unit)				
Measuring system	Measuring system on mo With additional direct m With measuring system	easuring system (mounte	ed in standard centre hole)	.0 .1 .9	6	
Direction of rotation	Any					
Mounting position	Any, standard table top: l (Please state other mour		ering)			
Indexing and repeat accuracy No indexing, one drive No indexing, two drives With indexing, one drive With two drives, with measuring system	Indexing accuracy					

Maximum axial runout of the table top	0.05 mm	
Maximum runout of the centre hole	0.05 mm	
Weight	FIBROMAT AT.1000 Gear motor Indexing unit	470 kg 95 kg 25 kg

Indexing times for FIBROMAT® AT.1000

AT.1000 v	with one drive								
45°	t _s in s	2.8	2.5	2.2	2.0	1.7	1.4	1.1	0.9
	J in kgm²	16,000	12,000	8,000	6,000	4,000	2,000	1,000	500
90°	t _s in s	4.0	3.6	3.1	2.9	2.6	2.0	1.6	1.5
	J in kgm²	16,000	12,000	8,000	6,000	4,000	2,000	1,000	500
180°	t _s in s	5.9	5.5	5.0	4.8	3.8	3.1	2.8	2.7
	J in kgm²	16,000	12,000	8,000	6,000	4,000	2,000	1,000	500

AT.1000) with two drive	S							
45°	t _s in s	1.9	1.7	1.5	1.4	1.2	0.9	0.8	0.7
	J in kgm²	16,000	12,000	8,000	6,000	4,000	2,000	1,000	500
90°	t _s in s	2.9	2.7	2.5	2.4	1.8	1.5	1.4	1.3
	J in kgm²	16,000	12,000	8,000	6,000	4,000	2,000	1,000	500
180°	t _s in s	4.8	4.6	4.4	4.3	3.0	2.7	2.5	2.5
	J in kgm²	16,000	12,000	8,000	6,000	4,000	2,000	1,000	500

The specified switching times do not include: Regulation time of $0.1\,\mathrm{sec}$, indexing time of $0.3\,\mathrm{sec}$. Further angels and indexing times can be calculated for you.

Load data for FIBROMAT® AT.1000

Perm. transport load on table top horizontal	12,000 kg
Perm. superstructure diameter	6,000 mm
Perm. force vertically on rotating table top	155,000 N
Perm. radial force on the rotating table top	64,000 N
Perm. tilting moment on rotating table top	50,000 Nm
Perm. tangential moment on table top (dynamic)	9,400 Nm

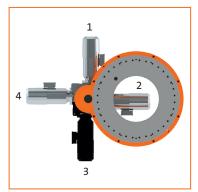
We would be pleased to provide a calculation of combined load data for your specific application.

Additional options for FIBROMAT $^{\circ}$ AT.1000

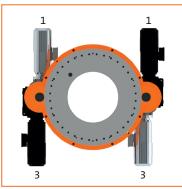
Drive unit Asynchronous motor (standard)	Indexing unit	
Drive unit Synchronous servomotor	Machine stands Height: 457 mm	пво
Drive inverter	Additional table top	

CAD data, technical data and planning documentation can be downloaded from www.fibro.com.

FIBRO



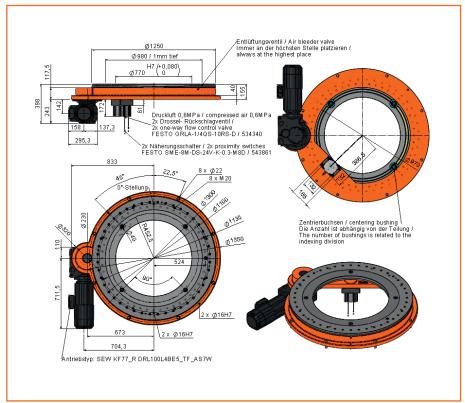
FIBROMAT AT.1250 Drive arrangement 10, 20, **30**, 40



FIBROMAT AT.1250 Drive arrangement 11, 13, **31**, 33

Dimensions of FIBROMAT® AT.1250

(Drive arrangement 180° with one drive; for other drive arrangements, diagrams or CAD data are available)



Technical data for FIBROMAT® AT.1250

	(2)	(3)	(Ð	(5) ((
AT.1250										

Table top dimension	Ø 1,250 mm						
Drive motor	1 drive without motor 1 drive with motor 1 drive with motor 1 drive with motor 2 drives without motor 2 drives with motor 2 drives with motor 2 drives with motor 2 drives with motor	drive with motor drive with motor drive with motor drives without motor drives without motor drives with motor					
Drive arrangement	See pictures above Special design						
Divisions Any, maximum 30	Without indexing unit With indexing unit for di Special division	/ith indexing unit for division XX, symmetrical arrangement					
Centre hole	Ø 770 mm Extended by 200 mm (no Special design	xtended by 200 mm (not combinable with standard indexing unit)					
Measuring system	With additional direct m	Measuring system on motor With additional direct measuring system (mounted in standard centre hole) With measuring system in special design					
Direction of rotation	Any						
Mounting position	Any, standard table top: l (Please state other mour	horizontal ating positions when orde	ering)				
Indexing and repeat accuracy No indexing, one drive No indexing, two drives With indexing, one drive With two drives, with measuring system	Indexing accuracy						

Maximum axial runout of the table top	0.07 mm	
Maximum runout of the centre hole	0.07 mm	
3	FIBROMAT AT.1250 Gear motor Indexing unit	635 kg 112 kg 25 kg

Indexing times for FIBROMAT® AT.1250

AT.1250	with one drive	1						,		
45°	t _s in s	3.7	3.4	3.1	2.8	2.5	2.3	2.0	17	1.3
	J in kgm²	35,000	30,000	25,000	20,000	16,000	12,000	8,000	4,000	2,000
90°	t _s in s	5.2	4.8	4.4	3.9	3.6	3.3	3.0	2.3	1.9
	J in kgm²	35,000	30,000	25,000	20,000	16,000	12,000	8,000	4,000	2,000
180°	t _s in s	7.3	6.9	6.4	5.9	5.6	5.3	4.4	3.5	3.0
	J in kgm²	35,000	30,000	25,000	20,000	16,000	12,000	8,000	4,000	2,000

AT.1250	with two drives									
45°	t _s in s	2.5	2.3	2.1	1.9	1.7	1.6	1.5	1.1	0.9
	J in kgm²	35,000	30,000	25,000	20,000	16,000	12,000	8,000	4,000	2,000
90°	t _s in s	3.5	3.3	3.1	2.9	2.7	2.6	2.1	1.7	1.5
	J in kgm²	35,000	30,000	25,000	20,000	16,000	12,000	8,000	4,000	2,000
180°	t _s in s	5.5	5.3	5.1	4.9	4.7	4.6	3.2	2.8	2.6
	J in kgm²	35,000	30,000	25,000	20,000	16,000	12,000	8,000	4,000	2,000

The specified switching times do not include: Regulation time of $0.1\,\mathrm{sec}$, indexing time of $0.3\,\mathrm{sec}$. Further angels and indexing times can be calculated for you.

Load data for FIBROMAT® AT.1250

Perm. transport load on table top horizontal	15,000 kg
Perm. superstructure diameter	7,500 mm
Perm. force vertically on rotating table top	172,000 N
Perm. radial force on the rotating table top	80,000 N
Perm. tilting moment on rotating table top	72,000 Nm
Perm. tangential moment on table top (dynamic)	12,900 Nm

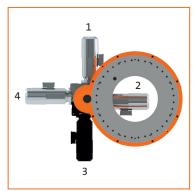
We would be pleased to provide a calculation of combined load data for your specific application.

Additional options for FIBROMAT $^{\circ}$ AT.1250

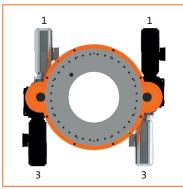
Drive unit Asynchronous motor (standard)	Indexing unit	
Drive unit Synchronous servomotor	Machine stands Height: 457 mm	пво
Drive inverter	Additional table top	

CAD data, technical data and planning documentation can be downloaded from www.fibro.com.

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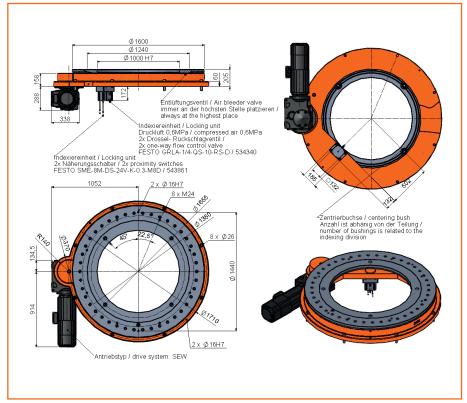
FIBROMAT AT.1600 Antriebsausrichtung 10, 20, **30**, 40



FIBROMAT AT.1600 Drive arrangement 11, 13, **31**, 33

Dimensions of FIBROMAT® AT.1600

(Drive arrangement 180° with one drive; for other drive arrangements, diagrams or CAD data are available)



Technical data for FIBROMAT® AT.1600

	(2)		3)	(Ð	(5) (6
AT.1600										

Table top dimension	Ø 1,600 mm						
Drive motor	1 drive without motor 1 drive with motor 1 drive with motor 1 drive with motor 2 drives without motor 2 drives with motor 2 drives with motor 2 drives with motor 2 drives with motor	drive with motor drive with motor drive with motor drives without motor drives with motor					
Drive arrangement	See pictures above Special design						
Divisions Any, maximum 38	Without indexing unit With indexing unit for di Special division	/ith indexing unit for division XX, symmetrical arrangement					
Centre hole	Ø 1,000 mm Extended by 200 mm (no Special design	xtended by 200 mm (not combinable with standard indexing unit)					
Measuring system	With additional direct m	Measuring system on motor With additional direct measuring system (mounted in standard centre hole) With measuring system in special design					
Direction of rotation	Any						
Mounting position	Any, standard table top: l (Please state other mour	horizontal ating positions when orde	ering)				
Indexing and repeat accuracy No indexing, one drive No indexing, two drives With indexing, one drive With two drives, with measuring system	Indexing accuracy ± 285" ± 60" ± 20" ± 10" ± 10"						

Maximum axial runout of the table top	0.1 mm	
Maximum runout of the centre hole	0.1 mm	
Weight	FIBROMAT AT.1600 Gear motor Indexing unit	1,400 kg 170 kg 25 kg

Indexing times for FIBROMAT® AT.1600

AT.1600 with one drive										
45°	t₅ in s	4.7	4.0	3.3	2.8	2.5	2.3	2.2	2.0	1.7
	J in kgm²	100,000	75,000	50,000	35,000	25,000	20,000	16,000	12,000	8.000
90°	t _s in s	6.6	5.7	4.7	4.0	3.8	3.4	3.1	2.8	2.5
	J in kgm²	100,000	75,000	50,000	35,000	25,000	20,000	16,000	12,000	8,000
180°	t _s in s	9.3	8.2	7.0	6.1	5.4	5.0	4.7	4.4	4.1
	J in kgm²	100,000	75,000	50,000	35,000	25,000	20,000	16,000	12,000	8,000

AT.1600 with two drives										
45°	t _s in s	3.1	2.7	2.2	1.9	1.8	1.6	1.5	1.3	1.2
	J in kgm²	100,000	75,000	50,000	35,000	25,000	20,000	16,000	12,000	8,000
90°	t _s in s	4.4	3.9	3.4	2.9	2.6	2.4	2.3	2.2	2.0
	J in kgm²	100,000	75,000	50,000	35,000	25,000	20,000	16,000	12,000	8,000
180°	t _s in s	6.8	6.3	5.7	4.5	4.2	4.0	3.9	3.8	3.7
	J in kgm²	100,000	75,000	50,000	35,000	25,000	20,000	16,000	12,000	8,000

The specified switching times do not include: Regulation time of 0.1 sec, indexing time of 0.3 sec. Further angels and indexing times can be calculated for you.

Load data for FIBROMAT® AT.1600

Perm. transport load on table top horizontal	25,000 kg
Perm. superstructure diameter	9,500 mm
Perm. force vertically on rotating table top	260,000 N
Perm. radial force on the rotating table top	220,000 N
Perm. tilting moment on rotating table top	135,000 Nm
Perm. tangential moment on table top (dynamic)	16,300 Nm

We would be pleased to provide a calculation of combined load data for your specific application.

Additional options for FIBROMAT® AT.1600

Drive unit Asynchronous motor (standard)	Indexing unit	
Drive unit Synchronous servomotor	Machine stands Height: 557 mm	FIBRO
Drive inverter	Additional table top	

CAD data, technical data and planning documentation can be downloaded from www.fibro.com.